

Parallel Kinematics: Type, Kinematics, And Optimal Design (Springer Tracts In Mechanical Engineering) By Xin-Jun Liu;Jinsong Wang

By Xin-Jun Liu;Jinsong Wang

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the robot is called a cylindrical parallel robot. The kinematics problems and The importance of optimal design for parallel Xin-Jun Liu was

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4 Robot Kinematics: In the first type, such as 2DOF planar manipulator or less DOF manipulator with parallel joint axes.

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<http://en.wikipedia.org/wiki/Kinematics>

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Mechanical engineering, transports Xin-Jun Liu, Jinsong Wang, 2006, p. 119 - 144 [Parallel mechanism; Optimum design; Performance atlas; Velocity;

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